

/*

H8042 USBサンプルプログラム

(C)2002 C.I.M

このサンプルは、H8の初期化と、USBの簡単な送受信の方法、および、
LCD、SCI、スイッチ、LEDのアクセスを行っています。

SCIはsci.c、LCDはlcd.cを参照してください。

USBの送受信は、usb.c内でリングバッファにデータの送受信を行っています。

ユーザーは、リングバッファにアクセスすることで簡単にデータの送受信ができます。

リングバッファのサイズは、現在送受信用とも256byteです。これを超えた分は捨てられます。

*/

```
/*  
*****  
#define USE_THREAD  
#define USE_H8_3052F  
*****  
#include <stdio.h>  
*****  
#ifdef USE_H8_3052F  
#define SLEEP_PER_SEC 16000.0  
*****  
#include "h83048.h"  
*****  
#else  
#define SLEEP_PER_SEC 100000000.0  
#include <conio.h> /* kbhit(), getche() */
```

```
#endif

#include <stdlib.h> /* malloc(), free(), rand() */

#define OK 1

#define NG 0

#ifdef USE_H8_3052F

/*****/

/*=====
=====

外部参照

=====
=====*/

/* start内に定義 */

extern void EnableInterrupt(void);
extern void DisableInterrupt(void);

/* lcd.c */

extern void InitLCD(void);
extern void PrintLCD(char *fmt,...);
extern void PutLCD(char c);

/* usb.c */

extern void InitUSB(void);
extern void DispUSBPort(void);

/* バッファ処理 */

extern int get_inbufflen(void);
extern int write_buff(char *p,int size);
extern int read_buff(char *p,int size);
```

```
/* sci.c */

extern void InitSCI(void);

extern void PrintSCI(char *fmt, ...);

extern int ScanSCI(void);

extern char GetSCI(void);

/* main.c内定義 */

void H8init(void);

int SetLED(int no,int onoff);

int GetSW(int no);

/*****/

#endif

/* 表示を表す列挙体宣言 */

enum PrintF

{

    Panel,

    InputCommand,

    Monitor

};

/* 表示を表す関数のプロトタイプ宣言 */

void PrintF(int mode, char *str);

/* 時間に使用する定数の宣言 */

#define WOVICLOCKSIZE 1000000.0
```

```

/* 時間を表す外部変数宣言 */
double woviClock;

/* 擬似スレッド定義 */
#ifdef USE_THREAD

/* 擬似スレッドに使用する定数の宣言 */
#define NULLTHREADID -1
#define INITCLOCKNO 1000001
#define STOPCLOCKNO 1000002

/* 構造体宣言 */
typedef struct tag_Thread
{
    /* 擬似スレッドID */
    int ID;

    /* 指定開始時 */
    double preClock;

    /* woviClockがpreClockからsetClock秒増えたらRunを呼ぶ */
    double setClock;

    /* Runが呼ばれた回数を調べるために使用(countUpNextRunが呼ばれた回数) */
    long count;

    /* List機能 */
    struct tag_Thread *previous;
    struct tag_Thread *next;
}Thread;

/* wovi用擬似インスタンス宣言 */
Thread woviThreadFirst;

```

```
Thread woviThreadLast;

/* 疑似メソッドとwovi用関数のプロトタイプ宣言 */
/* 宣言の順番は以下の通り */

#endif

double getClock(void);

#ifdef USE_THREAD

void nextRun(Thread *This, unsigned int ms);

void countUpNextRun(Thread *This, unsigned int ms);

void Run(Thread *This);

void Init(Thread *This);

void Destroy(Thread *This);

Thread *new_Thread(unsigned short int id);

void delete_(Thread *This);

void Start(Thread *This);

void Stop(Thread *This);

int Thread_checkAllDelete(void);

Thread *Thread_getThread(unsigned short int id);

Thread *Thread_Start(unsigned short int id);

void Thread_Toggle(unsigned short int id);

void woviRun(void);

void wovilnit(void);

/* タイマ関数 */

void wovi(double threadPerSec);

/* タイマ初期化関数 */

void initWOVI(void);

#endif
```

```
/* ミリ秒待ち関数 */  
void SleepMSec(double sleepPerSec, unsigned int ms);
```

```
/* 表示のための関数 */
```

```
void PrintF(int mode, char *str)
```

```
{
```

```
#ifdef USE_H8_3052F
```

```
static char buff[64];
```

```
#endif
```

```
switch(mode)
```

```
{
```

```
case Panel:
```

```
#ifdef USE_H8_3052F
```

```
if(strcmp(str, "¥n¥0") == 0)
```

```
{
```

```
    sprintf(str, "%s", "¥n¥f");
```

```
}
```

```
sprintf(buff, "%s", str);
```

```
PrintSCI("%s", buff);
```

```
PrintLCD(buff);
```

```
#else
```

```
printf("%s", str);
```

```
#endif
```

```
break;
```

```
case InputCommand:
```

```
#ifndef USE_H8_3052F
```

```
printf("%s", str);
```

```
#endif
```

```
break;

case Monitor:

#ifdef USE_H8_3052F
    sprintf(buff,"%s", str);
    PrintSCI("%s",buff);
    write_buff(buff,strlen(buff)+1);
#else
    printf("%s", str);
#endif

break;

default:
break;

}

return;

}

/* 時刻取得 */

double getClock(void)
{
    return woviClock;
}

#ifdef USE_THREAD

/* スレッドのvoid Sleep(int ms)の代用 */

void nextRun(Thread *This, unsigned int ms)
{
    This->preClock = woviClock;
```

```

    This->setClock = (((double) ms) / 1000);
    return;
}

/* スレッドのvoid Sleep(int ms)の代用 */
void countUpNextRun(Thread *This, unsigned int ms)
{
    nextRun(This, ms);
    This->count++;
}

#ifdef USE_H8_3052F
Thread th101;
Thread th102;
Thread th111;
Thread th112;
Thread th113;
Thread th114;
Thread th121;
Thread th122;
Thread th123;
Thread th124;
#endif

/* スレッドのコンストラクタの代用 */
Thread *new_Thread(unsigned short int id)
{
    Thread *List;
    Thread *new_List;
    List = &woviThreadFirst;
    while(List->next->next != NULL)

```



```
{  
    List = List->next;  
}  
  
#ifdef USE_H8_3052F  
    if(id == 1)  
    {  
        new_List = &th101;  
    }  
    else if(id == 2)  
    {  
        new_List = &th102;  
    }  
    else if(id == 11)  
    {  
        new_List = &th111;  
    }  
    else if(id == 12)  
    {  
        new_List = &th112;  
    }  
    else if(id == 13)  
    {  
        new_List = &th113;  
    }  
    else if(id == 14)  
    {  
        new_List = &th114;  
    }  
}
```

```

else if(id == 21)
{
    new_List = &th121;
}
else if(id == 22)
{
    new_List = &th122;
}
else if(id == 23)
{
    new_List = &th123;
}
else if(id == 24)
{
    new_List = &th124;
}
#else
    new_List = (Thread *)malloc(sizeof(Thread));
#endif
if(new_List == NULL)
{
    Printf(Panel, "¥n");
    Printf(Panel, "malloc failed");
    return NULL;
}
new_List->previous = List;
new_List->next = List->next;
new_List->next->previous = new_List;
List->next = new_List;

```

```

new_List->preClock = INITCLOCKNO;

new_List->setClock = 0;

new_List->ID = id;

new_List->count = 0;

/* スレッドのvoid init(void)の代用 */

Init(new_List);

return new_List;

}

/* スレッドのデストラクタの代用 */

void delete_(Thread *This)

{

    Destroy(This);

    This->previous->next = This->next;

    This->next->previous = This->previous;

#ifdef USE_H8_3052F

    free(This);

#endif

    return;

}

/* スレッドのvoid start(void)の代用 */

void Start(Thread *This)

{

    woviClock = getClock();

    This->preClock = woviClock;

    return;

}

```

```
/* スレッドのvoid stop(void)の代用 */
```

```
void Stop(Thread *This)
```

```
{  
    This->preClock = STOPCLOCKNO;  
    return;  
}
```

```
int Thread_checkAllDelete(void)
```

```
{  
    if(woviThreadFirst.next->next == NULL)  
    {  
        return OK;  
    }  
    else  
    {  
        return NG;  
    }  
}
```

```
Thread *Thread_getThread(unsigned short int id)
```

```
{  
    Thread *th;  
  
    if(woviThreadFirst.next->next == NULL)  
    {  
        return NULL;  
    }  
    else  
    {
```

```
th = woviThreadFirst.next;
do
{
    if(th->ID == id)
    {
        return th;
    }
    else
    {
        th = th->next;
    }
}while(th->next != NULL);
}
return NULL;
}
```

```
Thread *Thread_Start(unsigned short int id)
```

```
{
    Thread *th;

    th = Thread_getThread(id);
    if(th == NULL)
    {
        th = new_Thread(id);
        Start(th);
    }
    else if(th->preClock == STOPCLOCKNO)
    {
```

```
        Start(th);
    }
    return th;
}

void Thread_Toggle(unsigned short int id)
{
    Thread *th;

    th = Thread_getThread(id);
    if(th == NULL)
    {
        th = new_Thread(id);
        Start(th);
    }
    else if(th->preClock == STOPCLOCKNO)
    {
        Start(th);
    }
    else
    {
        delete_(th);
    }
    return;
}
```

```
/* Runを呼ぶタイミング */
```

```
void woviRun(void)
{
```

```

double woviClockCompare;

Thread *List;

Thread *next_List;

List = &woviThreadFirst;

List = List->next;

while(List->next != NULL)
{
    next_List = List->next;

    if((List->preClock != INITCLOCKNO) && (List->preClock != STOPCLOCKNO))
    {
        woviClockCompare = List->preClock + List->setClock;

        if(woviClock < List->preClock)
        {
            woviClockCompare -= WOVICLOCKSIZE;
        }

        if(woviClock >= woviClockCompare)
        {
            List->preClock = woviClock;

            /* スレッドのvoid run(void)の代用 */
            Run(List);
        }
    }

    List = next_List;
}

return;
}

```

/* 指定開始時OFF */

void wovlnit(void)

```

{
    woviThreadFirst.previous = NULL;
    woviThreadFirst.next = &woviThreadLast;
    woviThreadLast.previous = &woviThreadFirst;
    woviThreadLast.next = NULL;
    return;
}

/* タイマ関数 */
void wovi(double threadPerSec)
{
    woviClock += 1.0 / threadPerSec;
    if(woviClock >= WOVICLOCKSIZE)
    {
        Printf(Pannel, "%n");
        Printf(Pannel, "OVERWOVI");
        woviClock -= WOVICLOCKSIZE;
    }
    woviRun(); /* スレッドのためのRunを呼ぶタイミング */
    return;
}

/* タイマ初期化関数 */
void initWOVI(void)
{
    woviClock = 0.0;
    wovilnit(); /* スレッドのための指定開始時OFF */
    return;
}

```



```
#endif
```

```
/* ミリ秒待ち関数 */
```

```
void SleepMSec(double sleepPerSec, unsigned int ms)
```

```
{  
    double cnt;  
    double set;  
    cnt = 0.0;  
    set = ((double) ms) / 1000;  
    while(cnt < set)  
    {  
        cnt += 1.0 / sleepPerSec;  
    }  
    return;  
}
```

```
#ifdef USE_H8_3052F
```

```
/*=====*/
```

```
/*=====
```

```
main
```

```
-----  
H8の初期化などもまだなので、ここで行います。
```

```
この関数の終了はしないでください。
```

```
=====*/
```

```
/*
```

```
このサンプルは、USBから送られてきたデータを読み込んで、そのままHOSTへ返しています。
```

USBから送られてきたデータはLCDと、シリアルに出力しています。

また、シリアルから来たデータをLCD,UCBへ送信しています。

スイッチが押されると、LEDが一瞬点灯します。

```
*/  
  
/*****/  
  
#endif  
  
#ifdef USE_THREAD  
  
typedef struct tag_Count  
{  
    int cnt[2];  
}Count;  
  
Count Cnt;  
  
void Thread0(void)  
{  
    int i_cnt;  
    int i;  
    /* 擬似スレッドの擬似インスタンス宣言 */  
    Thread *th1;  
    Thread *th2;  
    th1 = new_Thread(1);  
    th2 = new_Thread(2);  
    /* 擬似スレッド開始 */  
    Printf(Pannel, "%n");  
    Printf(Pannel, "Thread 12 Start ");  
    /* 2秒待機 */  
    SleepMSec(SLEEP_PER_SEC, 2000);  
    Printf(Pannel, "%n");  
    Printf(Pannel, " ");
```

```
Start(th1);
Start(th2);
for(;;)
{
#ifdef USE_H8_3052F
    wovi(4000.0);
#else
    wovi(5000000.0);
#endif

    if(Cnt.cnt[0] >= 13)
    {
        i_cnt = 1;
        break;
    }
    else if(Cnt.cnt[1] >= 13)
    {
        i_cnt = 2;
        break;
    }
}

delete_(th1);
delete_(th2);

if(i_cnt == 1)
{
    Printf(Panel, "¥n");
    Printf(Panel, "GOAL!<1>WON  ");
}

else if(i_cnt == 2)
{
```

```

        Printf(Panel, "¥n");
        Printf(Panel, "GOAL!<2>WON  ");
    }
    return;
}

```

```

void Thread1(void)

```

```

{
    unsigned short int i;
    /* 疑似スレッドの疑似インスタンス宣言 */
    Thread *th[4];
    Printf(Panel, "¥n");
    Printf(Panel, "CountUp  ");
    /* 2秒待機 */
    SleepMSec(SLEEP_PER_SEC, 2000);
    /* 疑似スレッドの疑似インスタンス初期化 */
    for(i = 0; i < 4; i++)
    {
        th[i] = new_Thread(i + 11);
    }
    /* 2秒待機 */
    SleepMSec(SLEEP_PER_SEC, 2000);
    /* 疑似スレッド開始 */
    Printf(Panel, "¥n");
    Printf(Panel, "Start  ");
    for(i = 0; i < 4; i++)
    {
        Start(th[i]);
    }
}

```

```

for(;;)
{
    /* タイマー呼び出し */
#ifdef USE_H8_3052F
    wovi(4000.0);
#else
    wovi(5000000.0);
#endif

    if(Thread_checkAllDelete() == OK)
    {
        break;
    }
}

return;
}

void Thread2(void)
{
    int i;
    int j;
    char key;
    Thread *th21;
#ifdef USE_H8_3052F
    char sw[4];
    sw[0] = sw[1] = sw[2] = sw[3] = 0;    /* スイッチワーク初期化 */
#endif
    Printf(Panel, "¥n");
    Printf(Panel, "Toggle    ");
}

```

```
/* 2秒待機 */
```

```
SleepMSec(SLEEP_PER_SEC, 2000);
```

```
th21 = new_Thread(21);
```

```
Start(th21);
```

```
for(;;)
```

```
{
```

```
    key = ' ';
```

```
    /* タイマー呼び出し */
```

```
#ifdef USE_H8_3052F
```

```
    wovi(4000.0);
```

```
    /* ボタンが押された時にLCD,SCI,USBにメッセージを送る*/
```

```
    for(j=0;j<4;j++)
```

```
    {
```

```
        i = GetSW(j);
```

```
        if( ((sw[j]^1) & i) )          /* sw = off->onで条件成立 */
```

```
        {
```

```
            Thread_Toggle(j + 21);
```

```
        }
```

```
    }
```

```
#else
```

```
    wovi(50000.0);
```

```
    if(kbhit())
```

```
    {
```

```
        key = getche();
```

```
    }
```

```
    if(key == '1')
```

```

    {
        Thread_Toggle(21);
    }
    else if(key == '2')
    {
        Thread_Toggle(22);
    }
    else if(key == '3')
    {
        Thread_Toggle(23);
    }
    else if(key == '4')
    {
        Thread_Toggle(24);
    }
#endif

    if(Thread_checkAllDelete() == OK)
    {
        break;
    }
}
return;
}
#endif

/*****/
main()
{
/*****/

```

```
#ifdef USE_H8_3052F
```

```
/*  
*****  
*/
```

```
char sw[4];
```

```
/*  
*****  
*/
```

```
#endif
```

```
int i;
```

```
int j;
```

```
#ifdef USE_H8_3052F
```

```
/*  
*****  
*/
```

```
int f;
```

```
int cnt;
```

```
static char buff[64];
```

```
for(i=0;i<0x7fff;i++) {}
```

```
H8init(); /* H8 レジスタ初期化 */
```

```
InitSCI(); /* SCI1初期化(serial) */
```

```
InitLCD(); /* LCD初期化 */
```

```
/* LED OFF */
```

```
SetLED(0,0);
```

```
SetLED(1,0);
```

```
SetLED(2,0);
```

```
SetLED(3,0);
```

```
/*-----*/
```

```
/* USB初期化 */
```

```
InitUSB();
```

```
INTC.ISCR &= (-1^0x20); /* IRQ_5 センスコントロール Active Low */
```

```
INTC.IER |= 0x20; /* IRQ5 Enable */
```



```
/*-----*/
```

```
EnableInterrupt();          /* 割り込み許可 ccr */
```

```
f = 0;
```

```
PrintSCI("CPU MODE %02X\n",MDCR);    /* MODE 6 */
```

```
PrintLCD("%fReady!3052");          /* %fはLCDクリアに利用 */
```

```
sw[0] = sw[1] = sw[2] = sw[3] = 0;    /* スイッチワーク初期化 */
```

```
/*-----*/
```

```
#else
```

```
PrintF(Panel, "%n");
```

```
PrintF(Panel, "Hello BCC");
```

```
#endif
```

```
#ifdef USE_THREAD
```

```
/* タイマー初期化 */
```

```
initWOVI();
```

```
Thread0();
```

```
#endif
```

```
PrintF(Panel, "%n");
```

```
PrintF(Panel, "NEXT ");
```

```
/* 2秒待機 */
```

```
SleepMSec(SLEEP_PER_SEC, 2000);
```

```
#ifdef USE_THREAD
```

```
Thread1();
```

```
#endif
```

```
/* 2秒待機 */
```

```
SleepMSec(SLEEP_PER_SEC, 2000);
```

```

PrintF(Panel, "¥n");

PrintF(Panel, "NEXT      ");

/* 2秒待機 */

SleepMSec(SLEEP_PER_SEC, 2000);

#ifdef USE_THREAD

    Thread2();

#endif

/* 2秒待機 */

SleepMSec(SLEEP_PER_SEC, 2000);

PrintF(Panel, "¥n");

#ifdef USE_H8_3052F

/*****/

for(;;)
{
    /*-----*/

    /* ボタンが押された時にLCD,SCI,USBにメッセージを送る*/

    for(j=0;j<4;j++)
    {
        i = GetSW(j);

        if( ((sw[j]^1) & i) )          /* sw = off->onで条件成立 */
        {
            SetLED(j,1);              /* LED押した瞬間点灯 */

            sprintf(buff,"sw%u",j+1);

            PrintSCI("%s¥n",buff);

            write_buff(buff,strlen(buff)+1);    /* NULL(0x00)まで送信 */

            PrintLCD(buff);
        }
    }
}

```

```

else SetLED(j,0);

sw[j] = i;
}

/*-----*/
/* HOSTからのシリアル入力をLCD,USBに送る */
if( ScanSCI() ) /* SCIに受信データあり? */
{
    i = GetSCI(); /* シリアル入力 */
    PutLCD(i); /* LCD出力 */
    buff[0] = i;
    write_buff(buff,1); /* USB出力 */
}

/*-----*/
/* USBからデータを受信した場合、そのままHOSTへリダイレクトする */
if( get_inbufflen() ) /* 受信データあり? */
{
    cnt = read_buff(buff,64); /* データ取得(buffサイズは64byteまで) */
    PrintLCD("%f"); /* LCDクリア */
    PrintLCD(buff); /* LCDへ表示 */
    PrintSCI(buff); /* シリアル出力 */
    write_buff(buff,cnt); /* USBへリダイレクト */
}

/*-----*/
/* 動作確認のため点滅 */
SetLED(3,f);
f ^= 1;

```

```

        for(i=0;i<10000;i++) {}          /* 適当にウエイト */
    }

/*****/

#endif

    return;

/*****/

}

#ifdef USE_THREAD

void Repaint(void)
{
    int i;

#ifdef USE_H8_3052F
        Printf(Panel, "%n");
#else
        system("cls");
#endif
#endif

    for(i = 0; i < Cnt.cnt[0]; i++)
    {
        Printf(Panel, " ");
    }

    Printf(Panel, "<1>");
    Printf(Panel, "%n");
    for(i = 0; i < Cnt.cnt[1]; i++)
    {
        Printf(Panel, " ");
    }

    Printf(Panel, "<2>");

    return;
}

```

```

}
/*
 * 疑似スレッドの疑似メソッド関数
 */
/* スレッドのpublic void run()の代用 */
void Run(Thread *This)
{
    Thread *th11;

    if(This->ID == 1)
    {
        Repaint();
        Cnt.cnt[0]++;
        nextRun(This, (((rand() % 9) + 10) * 100));
    }
    else if(This->ID == 2)
    {
        Repaint();
        Cnt.cnt[1]++;
        nextRun(This, (((rand() % 9) + 10) * 100));
    }
    else if(This->ID == 11)
    {
        if(This->count == 1)
        {
            Printf(Pannel, "%n");
            Printf(Pannel, "<1>1st ");
            countUpNextRun(This, (1900 * 1));
        }
    }
}

```

```

}
else if(This->count == 2)
{
    Printf(Panel, "%n");
    Printf(Panel, "<1>2nd");
    Printf(Panel, "<1>Stop ");
    Stop(This);
}
else if(This->count == 3)
{
    Printf(Panel, "%n");
    Printf(Panel, "<1>3rd ");
    countUpNextRun(This, (1500 * 1));
}
else if(This->count == 4)
{
    Printf(Panel, "%n");
    Printf(Panel, "<1>Stop ");
    Stop(This);
}
}
else if(This->ID == 12)
{
    if(This->count == 1)
    {
        Printf(Panel, "%n");
        Printf(Panel, "<2>1st ");
        countUpNextRun(This, (1700 * This->ID));
    }
}

```

```

else if(This->count == 2)
{
    Printf(Panel, "%n");
    Printf(Panel, "<2>2nd    ");
    countUpNextRun(This, (1700 * This->ID));
}
else if(This->count == 3)
{
    Printf(Panel, "%n");
    Printf(Panel, "<2>3rd    ");
    countUpNextRun(This, (1700 * This->ID));
}
else
{
    Printf(Panel, "%n");
    Printf(Panel, "<2>Stop");
    Stop(This);
    delete_(This);
}
}
else if(This->ID == 13)
{
    if(This->count == 1)
    {
        Printf(Panel, "%n");
        Printf(Panel, "<3>1st    ");
        countUpNextRun(This, (1700 * This->ID));
    }
    else if(This->count == 2)

```

```

{
    Printf(Panel, "%n");
    Printf(Panel, "<3>2nd    ");
    countUpNextRun(This, (1700 * This->ID));
}
else if(This->count == 3)
{
    Printf(Panel, "%n");
    Printf(Panel, "<3>3rd    ");
    countUpNextRun(This, (1700 * This->ID));
}
else
{
    Printf(Panel, "%n");
    Printf(Panel, "<3>Stop");
    Stop(This);
    delete_(This);
}
}
else if(This->ID == 14)
{
    if(This->count == 1)
    {
        Printf(Panel, "%n");
        Printf(Panel, "<4>1st    ");
        countUpNextRun(This, (1500 * 4));
    }
    else if(This->count == 2)
    {

```



```

    Printf(Panel, "¥n");
    Printf(Panel, "<4>2nd");
    countUpNextRun(This, (1500 * 4));

    Printf(Panel, "<1>Start ");
    th11 = Thread_Start(11);
    countUpNextRun(th11, (1500 * 1));
}
else if(This->count == 3)
{
    Printf(Panel, "¥n");
    Printf(Panel, "<4>3rd ");
    countUpNextRun(This, (1500 * 4));
}
else if(This->count == 4)
{
    th11 = Thread_getThread(11);
    if(th11 != NULL)
    {
        delete_(th11);
    }

    Printf(Panel, "<4>Sto");
    Stop(This);
    delete_(This);
}
}
else if(This->ID == 21)

```

```
{
    Printf(Panel, "1");
    countUpNextRun(This, 2000);
}
else if(This->ID == 22)
{
    Printf(Panel, "2");
    countUpNextRun(This, 2000);
}
else if(This->ID == 23)
{
    Printf(Panel, "3");
    countUpNextRun(This, 2000);
}
else if(This->ID == 24)
{
    Printf(Panel, "4");
    countUpNextRun(This, 2000);
}

return;
}
```

/* スレッドのコンストラクタのpublic void init()の代用 */

```
void Init(Thread *This)
```

```
{
    if(This->ID == 1)
    {
        Cnt.cnt[0] = 0;
    }
}
```

```
        nextRun(This, (((rand() % 9) + 10) * 100));
    }
    else if(This->ID == 2)
    {
        Cnt.cnt[1] = 0;
        nextRun(This, (((rand() % 9) + 10) * 100));
    }
    else if(This->ID == 11)
    {
        Printf(Panel, "¥n");
        Printf(Panel, "<1>Init");
        countUpNextRun(This, (1500 * 1));
    }
    else if(This->ID == 12)
    {
        Printf(Panel, "<2>Init ");
        countUpNextRun(This, (1500 * This->ID));
    }
    else if(This->ID == 13)
    {
        Printf(Panel, "¥n");
        Printf(Panel, "<3>Init");
        countUpNextRun(This, (1500 * This->ID));
    }
    else if(This->ID == 14)
    {
        Printf(Panel, "<4>Init ");
        countUpNextRun(This, (1500 * This->ID));
    }
}
```

```
else if(This->ID == 21)
{
    Printf(Panel, "¥n");
    Printf(Panel, "<1>Init    ");
    Printf(Panel, "¥n");
    countUpNextRun(This, 2000);
}
else if(This->ID == 22)
{
    Printf(Panel, "¥n");
    Printf(Panel, "<2>Init    ");
    Printf(Panel, "¥n");
    countUpNextRun(This, 2000);
}
else if(This->ID == 23)
{
    Printf(Panel, "¥n");
    Printf(Panel, "<3>Init    ");
    Printf(Panel, "¥n");
    countUpNextRun(This, 2000);
}
else if(This->ID == 24)
{
    Printf(Panel, "¥n");
    Printf(Panel, "<4>Init    ");
    Printf(Panel, "¥n");
    countUpNextRun(This, 2000);
}
return;
```

```
}
```

```
/* スレッドのデストラクタの代用 */
```

```
void Destroy(Thread *This)
```

```
{
```

```
    if(This->ID == 11)
```

```
    {
```

```
        Printf(Panel, "%n");
```

```
        Printf(Panel, "<1>Destroy");
```

```
    }
```

```
    else if(This->ID == 12)
```

```
    {
```

```
        Printf(Panel, "<2>Destro");
```

```
    }
```

```
    else if(This->ID == 13)
```

```
    {
```

```
        Printf(Panel, "<3>Destro");
```

```
    }
```

```
    else if(This->ID == 14)
```

```
    {
```

```
        Printf(Panel, "%n");
```

```
        Printf(Panel, "<4>Destroy  ");
```

```
    }
```

```
    if(This->ID == 21)
```

```
    {
```

```
        Printf(Panel, "%n");
```

```
        Printf(Panel, "<1>Destroy  ");
```

```
        Printf(Panel, "%n");
```

```

}
else if(This->ID == 22)
{
    Printf(Panel, "%n");
    Printf(Panel, "<2>Destroy  ");
    Printf(Panel, "%n");
}
else if(This->ID == 23)
{
    Printf(Panel, "%n");
    Printf(Panel, "<3>Destroy  ");
    Printf(Panel, "%n");
}
else if(This->ID == 24)
{
    Printf(Panel, "%n");
    Printf(Panel, "<4>Destroy  ");
    Printf(Panel, "%n");
}
return;
}
#endif

#ifdef USE_H8_3052F

/*****/

/*=====
=====

```

LEDコントロール

int SetLED(int no,int onoff)

int no LEDナンバー 0~3

int onoff 0=OFF,1=ON

戻り値 以前のLEDの状態 (0=OFF,else=ON)

LEDをコントロールします。

=====

====*/

int SetLED(int no,int onoff)

{

int f;

f = PB.DR&(1<<no);

if(onoff == 0) PB.DR |= (1<<no); /* off (1) */

else PB.DR &= 0xff^(1<<no); /* on (0) */

return(f);

}

/*=====

=====

SW状態取得

int GetSW(int no)

int no SWナンバー 0~3

戻り値 SWの状態(0=OFF,else=ON)

SWの状態を取得します。

=====

====*/

int GetSW(int no)

```
{  
    return( ((PA.DR&(1<<no))?0:1) );  
}
```

/*=====

=====

H8初期化

BUSモードや、ポートの初期化

P1	bit1	BUS	USB A0
P3		BUS	USB D7..0
P6	bit4	BUS	USB RD
P6	bit5	BUS	USB WR
P8	bit2	BUS	USB CS
P9	bit5	BUS	USB INT(IRQ5)
P9	bit3	BUS	RS232C
P9	bit1	BUS	RS232C
PA	bit0..3	IN	SW0..3
PB	bit0..3	OUT	LED0..3 LCD DB4..7
PB	bit4	OUT	LCD RS
PB	bit7	OUT	LCD E

=====

====*/

void H8init()


```
{  
  
    BSC.ABWCR = 0x06;           /* 8bit BUS MODE */  
  
    P1.DDR = 0xff;             /* all OUT      */  
    P2.DDR = 0xff;             /* all OUT      */  
    P2.PCR = 0x00;             /* Pull up off  */  
    P5.DDR = 0xff;             /* all OUT      */  
    P5.PCR = 0x00;             /* Pull up off  */  
    P6.DDR = 0xff;             /* all OUT      */  
    P9.DDR = 0xdf;             /* Bit5 IN      */  
    P8.DDR = 0xff;             /* all OUT      */  
    PA.DDR = 0xf0;             /* bit7..4 out , bit3..0 in */  
    PB.DDR = 0xff;             /* bit7..0 out */  
  
}
```

```
/*  
*****  
*/
```

```
#endif
```

```
.CPU 300HA
.SECTION V, CODE, LOCATE=H'000000
.IMPORT _main
.IMPORT _usb_int

.DATA.L _start ;リセットベクトル
.DATA.L int_error
.DATA.L int_error
.DATA.L int_error

.DATA.L int_error
.DATA.L int_error
.DATA.L int_error
.DATA.L int_error

.DATA.L int_error
.DATA.L int_error
.DATA.L int_error
.DATA.L int_error
```

```
IRQ0: .DATA.L int_error
IRQ1: .DATA.L int_error
IRQ2: .DATA.L int_error
IRQ3: .DATA.L int_error
IRQ4: .DATA.L int_error
IRQ5: .DATA.L usb_interrupt
```

.SECTION P, CODE, ALIGN=2

_start:

mov.l #H'0FFFF10, er7

;初期化付きデータを使用する場合、RAMに転送する

mov.l #H'8000, er0 ;転送元(8000)

mov.l #H'0FFEF10, er1 ;転送先

mov.l #DATA_END, er2 ;転送終了

init_loop:

cmp.l er1, er2

beq init_end

mov.b @er0+, r3l

mov.b r3l, @er1

inc.l #1, er1

bra init_loop

init_end:

jsr @_main

;割り込み未使用

int_error:

rte

usb_interrupt:

push.l er0

push.l er1

push.l er2

push.l er3

push.l er4

```
push.l er5
push.l er6
jsr  @_usb_int
pop.l er6
pop.l er5
pop.l er4
pop.l er3
pop.l er2
pop.l er1
pop.l er0
rte
```

```
;-----
```

```
; 割り込み許可、禁止ルーチン
```

```
.EXPORT _EnableInterrupt,_DisableInterrupt
```

```
_EnableInterrupt:
```

```
andc.b #H'3f,ccr
```

```
rts
```

```
_DisableInterrupt:
```

```
orc.b #H'c0,ccr
```

```
rts
```

```
;-----
```

```
.SECTION  D,DATA
```

```
.SECTION  B,DATA
```

DATA_END: .RES.W 1

.END

OUTPUT usbtest
PRINT usbtest
INPUT start,main,sci,lcd,usb
LIB c:\h8\akic\c38hab
START R(0FFEF10),P(200),D(8000),C(9000)
ROM (D,R)
EXIT

```
set path=c:\h8\akic;c:\h8\akiasm;%path%
del err.txt
cc38h -cpu=300ha -include=c:\h8\akic,c:\h8\usb main.c >> err.txt
cc38h -cpu=300ha -include=c:\h8\akic,c:\h8\usb usb.c >> err.txt
cc38h -cpu=300ha -include=c:\h8\akic,c:\h8\usb sci.c >> err.txt
cc38h -cpu=300ha -include=c:\h8\akic,c:\h8\usb lcd.c >> err.txt
a38h start.asm >> err.txt
l38h -subcommand=usbtest.sub >> err.txt
c38h usbtest >> err.txt
err.txt
```

H8/300H ASSEMBLER (Evaluation software) Ver.1.0

*****TOTAL ERRORS 0

*****TOTAL WARNINGS 0

H8/300H LINKAGE EDITOR (Evaluation software) Ver.1.0

: OUTPUT usbtest

: PRINT usbtest

: INPUT start,main,sci,lcd,usb

: LIB c:\h8\akic\c38hab

: START R(0FFEF10),P(200),D(8000),C(9000)

: ROM (D,R)

: EXIT

LINKAGE EDITOR COMPLETED

H8/300H OBJECT CONVERTER (Evaluation software) Ver.1.0

OBJECT CONVERTER COMPLETED

LINK COMMAND LINE

LNK -subcommand=usbtest.sub

LINK SUBCOMMANDS

OUTPUT usbtest
 PRINT usbtest
 INPUT start,main,sci,lcd,usb
 LIB c:\h8\akic\c38hab
 START R(0FFEF10),P(200),D(8000),C(9000)
 ROM (D,R)
 EXIT

*** LINKAGE EDITOR LINK MAP LIST ***

SECTION NAME	START UNIT NAME	END UNIT NAME	LENGTH MODULE NAME
--------------	--------------------	------------------	-----------------------

ATTRIBUTE : CODE NOSHR

V	H'00000000	- H'00000047	H'00000048
	start		start

* TOTAL ADDRESS * H'00000000 - H'00000047 H'00000048

ATTRIBUTE : CODE NOSHR

P	H'00000200	- H'00000271	H'00000072
	start		start
	H'00000272	- H'0000164D	H'000013DC
	main		main
	H'0000164E	- H'0000171F	H'000000D2
	sci		sci
	H'00001720	- H'0000195D	H'0000023E
	lcd		lcd
	H'0000195E	- H'0000244F	H'00000AF2
	usb		usb
	H'00002450	- H'00002489	H'0000003A
	rand		rand
	H'0000248A	- H'000024E7	H'0000005E
	sprintf		sprintf
	H'000024E8	- H'00002511	H'0000002A

H'00002512	-	strcmp	H'0000001C	strcmp
		strlen		strlen
H'0000252E	-	H'0000252D	H'00000030	
		vsprintf		vsprintf
H'0000255E	-	H'00002837	H'000002DA	
		addd3		addd3
H'00002838	-	H'00002A69	H'00000232	
		divd3		divd3
H'00002A6A	-	H'00002A75	H'0000000C	
		eqd3		eqd3
H'00002A76	-	H'00002A85	H'00000010	
		ged3		ged3
H'00002A86	-	H'00002A95	H'00000010	
		ltd3		ltd3
H'00002A96	-	H'00002AB3	H'0000001E	
		mv83		mv83
H'00002AB4	-	H'00002AC1	H'0000000E	
		ned3		ned3
H'00002AC2	-	H'00002AE3	H'00000022	
		spregld3		spregld3
H'00002AE4	-	H'00002B0B	H'00000028	
		spregsv3		spregsv3

H8/300H LINKAGE EDITOR (Evaluation software) Ver.1.0 PAGE : 2

*** LINKAGE EDITOR LINK MAP LIST ***

SECTION NAME	START	-	END	LENGTH
	UNIT NAME			MODULE NAME

ATTRIBUTE : CODE NOSHR

P	H'00002B0C	-	H'00002B37	H'0000002C
			utod3	utod3
	H'00002B38	-	H'000048E5	H'00001DAE
			_fmtout	_fmtout
	H'000048E6	-	H'000049A1	H'000000BC
			cmpd3	cmpd3
	H'000049A2	-	H'000049C7	H'00000026
			divl3	divl3
	H'000049C8	-	H'000049E7	H'00000020
			mull3	mull3
	H'000049E8	-	H'00004DCD	H'000003E6
			_dti	_dti
	H'00004DCE	-	H'00004F71	H'000001A4
			_its	_its
	H'00004F72	-	H'00004FCB	H'0000005A
			memcpy	memcpy
	H'00004FCC	-	H'00005007	H'0000003C
			divul3	divul3
	H'00005008	-	H'0000502F	H'00000028
			_allzero	_allzero

H'00005030	-	H'00005127	H'000000F8
		_calcnpw	_calcnpw
H'00005128	-	H'000051CB	H'000000A4
		_log10	_log10
H'000051CC	-	H'00005243	H'00000078
		_lsfts	_lsfts
H'00005244	-	H'00005271	H'0000002E
		_pow5	_pow5
H'00005272	-	H'000052EB	H'0000007A
		_rsfts	_rsfts
H'000052EC	-	H'00005397	H'000000AC
		_sub	_sub
H'00005398	-	H'0000543B	H'000000A4
		_unpack	_unpack
H'0000543C	-	H'00005479	H'0000003E
		memcmp	memcmp
H'0000547A	-	H'00005501	H'00000088
		_mult64	_mult64
H'00005502	-	H'00005663	H'00000162
		_power	_power
H'00005664	-	H'0000574D	H'000000EA
		_rnd	_rnd
H'0000574E	-	H'000057E9	H'0000009C
		_setsbit	_setsbit
H'000057EA	-	H'000058EF	H'00000106
		frexp	frexp

H8/300H LINKAGE EDITOR (Evaluation software) Ver.1.0 PAGE : 3

*** LINKAGE EDITOR LINK MAP LIST ***

SECTION NAME	START	-	END	LENGTH
	UNIT NAME			MODULE NAME

ATTRIBUTE : CODE NOSHR

P	H'000058F0	-	H'00005A25	H'00000136
			modf	modf
	H'00005A26	-	H'00005A47	H'00000022
			dslc3	dslc3
	H'00005A48	-	H'00005A69	H'00000022
			dsruc3	dsruc3
	H'00005A6A	-	H'00005AE3	H'0000007A
			dtol3	dtol3
	H'00005AE4	-	H'00005B19	H'00000036
			itod3	itod3
	H'00005B1A	-	H'00005E07	H'000002EE
			muld3	muld3
	H'00005E08	-	H'00005E59	H'00000052
			_duchek	_duchek
	H'00005E5A	-	H'00005EAB	H'00000052
			_lsft	_lsft
	H'00005EAC	-	H'00006039	H'0000018E

```

      _mult                _mult
H'0000603A - H'000060D5 H'0000009C
      _pow10              _pow10
H'000060D6 - H'0000611D H'00000048
      _add                 _add
H'0000611E - H'0000614D H'00000030
      memset              memset

```

* TOTAL ADDRESS * H'00000200 - H'0000614D H'00005F4E

ATTRIBUTE : DATA NOSHR ROM

```

D          H'00008000 - H'00008000 H'00000000
          start                start
H'00008000 - H'0000800F H'00000010
          usb                  usb

```

* TOTAL ADDRESS * H'00008000 - H'0000800F H'00000010

ATTRIBUTE : DATA NOSHR

```

C          H'00009000 - H'000092F5 H'000002F6
          main                main
H'000092F6 - H'000093AF H'000000BA
          usb                  usb
H'000093B0 - H'000093B7 H'00000008
          _fmtout            _fmtout

```

H8/300H LINKAGE EDITOR (Evaluation software) Ver.1.0 PAGE : 4

*** LINKAGE EDITOR LINK MAP LIST ***

SECTION NAME	START	END	LENGTH
	UNIT NAME	MODULE NAME	

ATTRIBUTE : DATA NOSHR

C	H'000093B8	- H'000094B7	H'00000100
		_ctype	_ctype
	H'000094B8	- H'0000953F	H'00000088
		_its	_its
	H'00009540	- H'00009547	H'00000008
		_log10	_log10
	H'00009548	- H'00009627	H'000000E0
		_pow5	_pow5
	H'00009628	- H'0000972B	H'00000104
		_power	_power
	H'0000972C	- H'00009733	H'00000008
		frexp	frexp
	H'00009734	- H'0000973B	H'00000008
		modf	modf

* TOTAL ADDRESS * H'00009000 - H'0000973B H'0000073C

ATTRIBUTE : DATA NOSHR RAM

R H'00FFEF10 - H'00FFEF10 H'00000000
start start
H'00FFEF10 - H'00FFEF1F H'00000010
usb usb

* TOTAL ADDRESS * H'00FFEF10 - H'00FFEF1F H'00000010

ATTRIBUTE : DATA NOSHR

B H'00FFEF20 - H'00FFEF21 H'00000002
start start
H'00FFEF22 - H'00FFF115 H'000001F4
main main
H'00FFF116 - H'00FFF165 H'00000050
sci sci
H'00FFF166 - H'00FFF1A5 H'00000040
lcd lcd
H'00FFF1A6 - H'00FFF479 H'000002D4
usb usb
H'00FFF47A - H'00FFF4B5 H'0000003C
_fmtout _fmtout
H'00FFF4B6 - H'00FFF4B9 H'00000004
_rnext _rnext
H'00FFF4BA - H'00FFF4BB H'00000002
_errno _errno

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*** LINKAGE EDITOR LINK MAP LIST ***

SECTION NAME	START	END	LENGTH
	UNIT NAME		MODULE NAME

* TOTAL ADDRESS * H'00FFEF20 - H'00FFF4BB H'0000059C

H8/300H LINKAGE EDITOR (Evaluation software) Ver.1.0 PAGE : 1

*** LINKAGE EDITOR EXTERNALLY DEFINED SYMBOLS LIST ***

SYMBOL NAME	ADDR	TYPE
\$ADDD\$3	H'00002628	DAT
\$CMPD\$3	H'000048E6	DAT
\$DIVD\$3	H'000028D2	DAT
\$DIVL\$3	H'000049A2	DAT

\$DIVUL\$3	H'00004FCC	DAT
\$DSLCL\$3	H'00005A26	DAT
\$DSRUC\$3	H'00005A48	DAT
\$DTOL\$3	H'00005A6A	DAT
\$EQD\$3	H'00002A6A	DAT
\$GED\$3	H'00002A76	DAT
\$ITOD\$3	H'00005AE4	DAT
\$LTD\$3	H'00002A86	DAT
\$MULD\$3	H'00005BD0	DAT
\$MULL\$3	H'000049C8	DAT
\$MV8\$3	H'00002A96	DAT
\$NED\$3	H'00002AB4	DAT
\$SUBD\$3	H'000025F8	DAT
\$UTOD\$3	H'00002B0C	DAT
\$sp_regld\$3	H'00002AC2	DAT
\$sp_regsv\$3	H'00002AE4	DAT
_ClearLCD	H'0000183E	ENT
_Cnt	H'00FFF0D2	DAT
_Destroy	H'0000147A	ENT
_DisableInterrupt	H'0000026E	DAT
_DispUSBPort	H'00001A6E	ENT
_EnableInterrupt	H'0000026A	DAT
_GetSCI	H'0000167E	ENT
_GetSW	H'000015FC	ENT
_H8init	H'00001622	ENT
_Init	H'0000127C	ENT
_InitLCD	H'000017CE	ENT
_InitSCI	H'0000164E	ENT
_InitUSB	H'00001974	ENT
_LCDOut4	H'00001776	ENT
_LocateLCD	H'0000187E	ENT
_PrintF	H'00000272	ENT
_PrintLCD	H'000018A2	ENT
_PrintSCI	H'0000169E	ENT
_PutLCD	H'00001852	ENT
_PutSCI	H'0000166E	ENT
_Repaint	H'00000D82	ENT
_Run	H'00000DF6	ENT
_ScanSCI	H'0000168E	ENT
_SetLED	H'000015AE	ENT
_SleepMSec	H'000007B8	ENT
_Start	H'00000518	ENT
_Stop	H'00000546	ENT
_Thread0	H'0000083C	ENT
_Thread1	H'00000948	ENT
_Thread2	H'00000A46	ENT
_Thread_Start	H'000005B8	ENT

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*** LINKAGE EDITOR EXTERNALLY DEFINED SYMBOLS LIST ***

SYMBOL NAME	ADDR	TYPE
_Thread_Toggle	H'000005F6	ENT

_Thread_checkAllDelete	H'00000564	ENT
_Thread_getThread	H'0000057E	ENT
__add	H'000060D6	ENT
__allzero	H'00005008	ENT
__calcnpw	H'00005030	ENT
__ctype	H'000093B8	DAT
__dti	H'000049E8	ENT
__duchek	H'00005E08	ENT
__errno	H'00FFF4BA	DAT
__fmtout	H'00002B38	ENT
__its	H'00004DCE	ENT
__log10	H'00005128	ENT
__lsft	H'00005E5A	ENT
__lsfts	H'000051CC	ENT
__mult	H'00005EAC	ENT
__mult64	H'0000547A	ENT
__pow10	H'0000603A	ENT
__pow5	H'00005244	ENT
__power	H'00005502	ENT
__rnd	H'00005664	ENT
__rnext	H'00FFF4B6	DAT
__rsfts	H'00005272	ENT
__setsbit	H'0000574E	ENT
__sub	H'000052EC	ENT
__unpack	H'00005398	ENT
_countUpNextRun	H'0000039C	ENT
delete	H'000004E4	ENT
_frexp	H'000057EA	ENT
_getClock	H'00000346	ENT
_get_inbufflen	H'00002428	ENT
_get_outbufflen	H'0000243C	ENT
_initWOVI	H'000007A4	ENT
_init_usbbuff	H'0000228C	ENT
_main	H'00000B06	ENT
_memcmp	H'0000543C	ENT
_memcpy	H'00004F72	ENT
_memset	H'0000611E	ENT
_modf	H'000058F0	ENT
_new_Thread	H'000003BC	ENT
_nextRun	H'00000358	ENT
_rand	H'00002450	ENT
_read_buff	H'000023CA	ENT
_read_outbuff	H'0000236C	ENT
_sprintf	H'0000248A	ENT
_strcmp	H'000024E8	ENT
_strlen	H'00002512	ENT
_th101	H'00FFEFA6	DAT
_th102	H'00FFFC4	DAT
_th111	H'00FFFEFE2	DAT
_th112	H'00FFF000	DAT

SYMBOL NAME	ADDR	TYPE
_th113	H'00FFF01E	DAT
_th114	H'00FFF03C	DAT
_th121	H'00FFF05A	DAT
_th122	H'00FFF078	DAT
_th123	H'00FFF096	DAT
_th124	H'00FFF0B4	DAT
_usb_int	H'00001AD2	ENT
_vsprintf	H'0000252E	ENT
_wovi	H'0000072E	ENT
_woviClock	H'00FFEF22	DAT
_woviInit	H'000006FC	ENT
_woviRun	H'0000063A	ENT
_woviThreadFirst	H'00FFEF2A	DAT
_woviThreadLast	H'00FFEF48	DAT
_write_buff	H'00002306	ENT
_write_inbuff	H'000022AA	ENT

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